

Graph Models of Information Spreading in Wireless Networks

Alberto Pettarin

pettarin@dei.unipd.it

XXIV Series — ICT Curriculum

Committee: Prof. R. Giancarlo, Prof. A. Panconesi, Prof. D. Rocchesso (chair)

Wireless Networks



Mobile Devices Networks



Vehicular Networks



Wildlife Surveillance Systems



Field Operations

Motivation

Ad hoc/sensor/vehicular/personal networks will be the future of distributed computing (as efficiency + integration \uparrow , cost-per-unit \downarrow)

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We need **theoretical knowledge** of the fundamental properties of these systems, in order to design efficient and scalable algorithms

Thesis Objectives and Results

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- ▶ Define **graph models** of interesting networks
- ▶ **Analyze** their properties related to **information spreading**
- ▶ Design **efficient algorithms** using this knowledge

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Results

Characterization of:

- ▶ **Expansion and diameter** of Bluetooth networks
- ▶ **Flooding time** in **dynamic** Bluetooth networks
- ▶ **Broadcast time** in **sparse mobile networks** and several related scenarios

Outline of the Presentation

- ▶ Bluetooth Networks
 - ▶ Bluetooth Topology Model
 - ▶ Expansion and Diameter
 - ▶ Flooding Time in Dynamic BT Networks

- ▶ Dynamic Graphs
 - ▶ Random Walker Model
 - ▶ Broadcast Time
 - ▶ Related Scenarios

- ▶ Conclusions



Bluetooth Networks



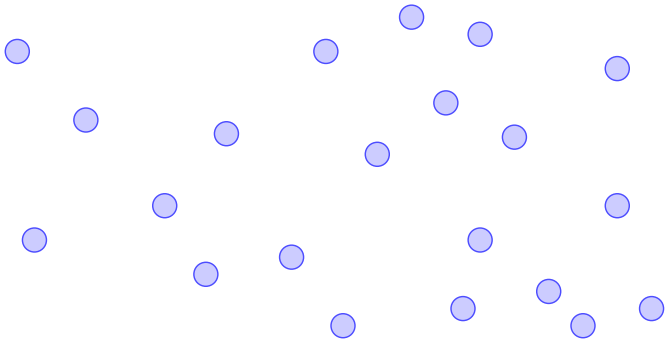
Bluetooth Technology



- ▶ Technology for **wireless communication** introduced as cable replacement for small PANs connecting laptops, mobile phones, PDAs, etc.
- ▶ Arguments in favor of BT for **large ad-hoc scenarios**:
 - ▶ cheap and easily integrable
 - ▶ good data rate/energy consumption tradeoff
 - ▶ wide adoption

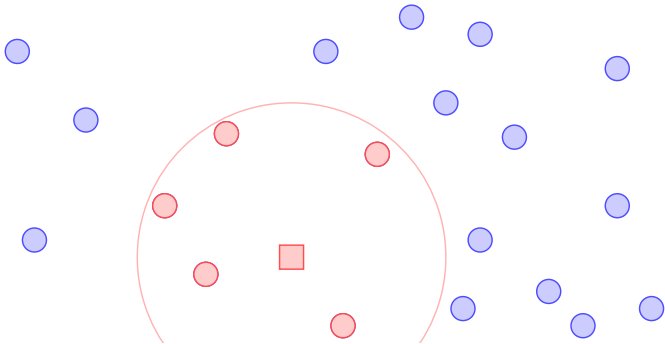
Bluetooth Technology: Network Organization/Formation

- ▶ **Piconet:** 1 master, ≤ 7 slaves
- ▶ **Scatternet:** interconnection of piconets through gateways to form multi-hop ad hoc network; three phases: device discovery, piconet formation, scatternet formation



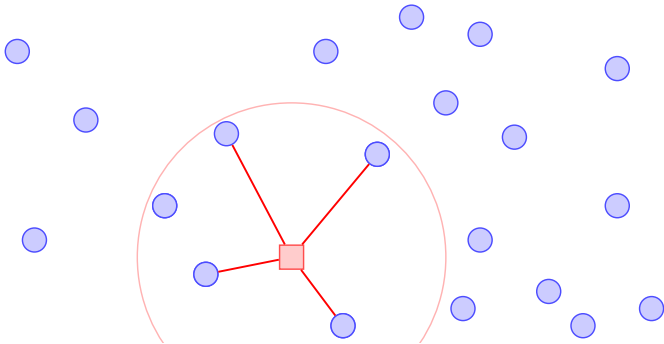
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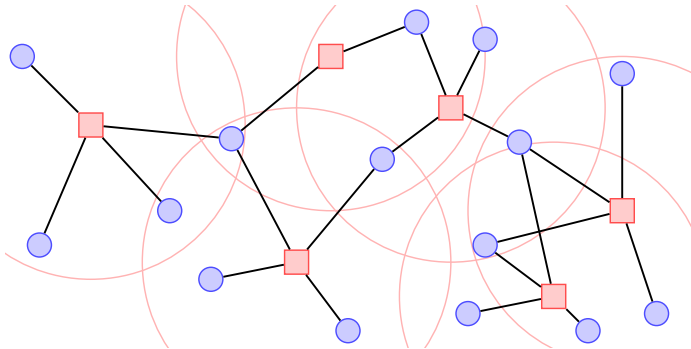
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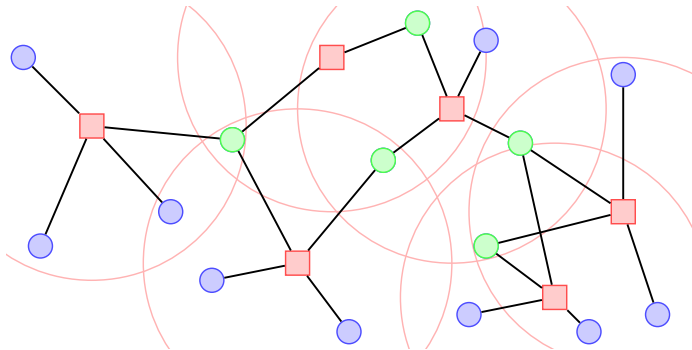
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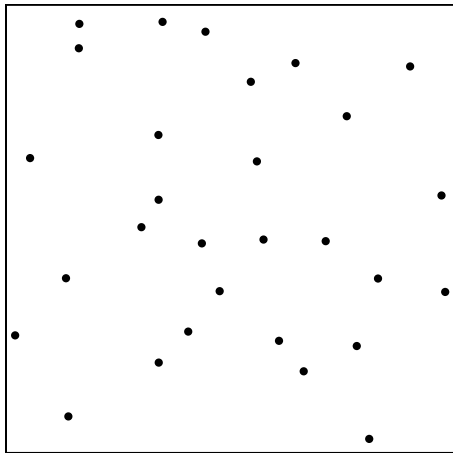


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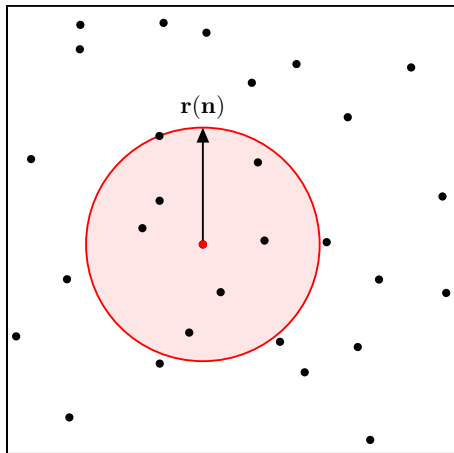
Bluetooth Topology: Mathematical Model



Graph $BT(r(n), c(n))$

- ▶ n nodes (*devices*) placed at random in $[0, 1]^2$

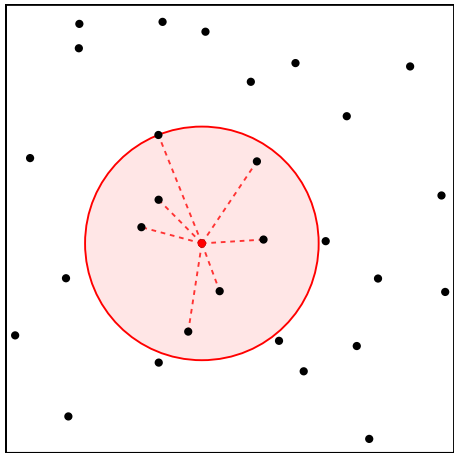
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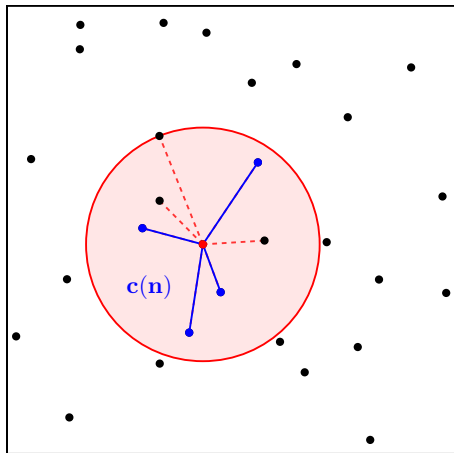
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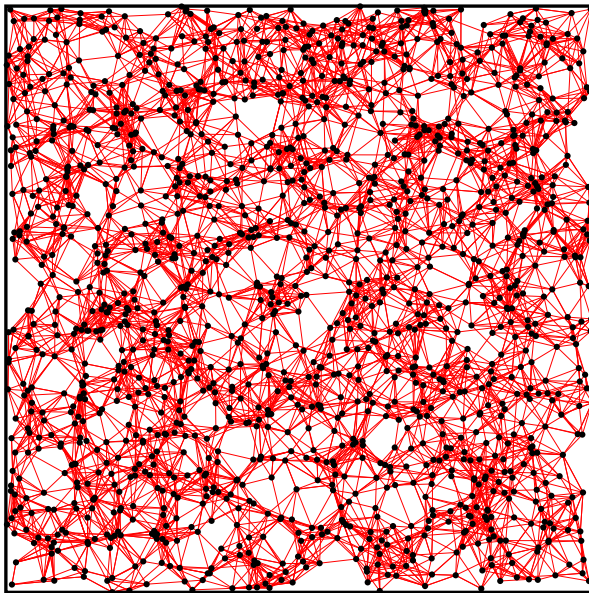
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- ▶ visibility range $r(n)$
- ▶ among all visible nodes

Bluetooth Topology: Mathematical Model



Graph $BT(r(n), c(n))$

- ▶ n nodes (devices) placed at random in $[0, 1]^2$
- ▶ visibility range $r(n)$
- ▶ among all visible nodes each device independently selects $c(n)$ random neighbors (it selects all visible nodes if $< c(n)$)



$BT(0.075, 5)$ with $n = 1500$ nodes.

Relevant Questions

How many neighbors should each device discover, in order for BT to exhibit:

- ▶ **connectivity** (i.e., single connected component)?
- ▶ **good expansion** (i.e., high bandwidth)?
- ▶ **low diameter** (i.e., low latency)?

Previous Work

- ▶ [Penrose 03]: $r(n) = \Omega\left(\sqrt{\log n/n}\right)$ necessary and sufficient to achieve **connectivity** w.h.p., when each node connects to *all* visible nodes (**Random Geometric Graph** or **visibility graph**)
- ▶ [Panconesi et al., 04]: for $r(n) = \Theta(1)$, $c(n) = \Theta(1)$ suffices to attain **high expansion** w.h.p.
- ▶ [Dubhashi et al., 05]: for $r(n) = \Theta(1)$, $c(n) = 2$ suffices to attain **connectivity** w.h.p.

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Setting $r(n) = \Theta(1)$ implies that each node sees a constant fraction of all other nodes \Rightarrow **unfeasible for large n .**

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Analysis for $r(n)$ decreasing in n is needed!

Previous Work (cont'd)

Theorem (Crescenzi, Nocentini, Pietracaprina, Pucci, 2007)

There exist two positive real constants γ_1, γ_2 such that if

$$r(n) \geq \gamma_1 \sqrt{\frac{\log n}{n}} \quad \text{and} \quad c(n) = \gamma_2 \log \frac{1}{r(n)}$$

*then $BT(r(n), c(n))$ is **connected** w.h.p.*

Our Contribution [ESA'09, ToCS'12]

- ▶ Tight bounds on the **expansion** of $BT(r(n), c(n))$
- ▶ Tight bounds (up to a logarithmic additive term) on the **diameter** of $BT(r(n), c(n))$
- ▶ An upper bound on the **flooding time** in a dynamic version of $BT(r(n), c(n))$, where nodes move over time

Expansion of $BT(r(n), c(n))$

Definition (Node Expansion)

$$\lambda(s) = \min_{S \subseteq V: |S|=s} \frac{|\Gamma(S) - S|}{s}, \quad 1 \leq s \leq |V|/2.$$

Theorem (Expansion of BT)

Let $m = \Theta(nr^2(n))$. Then, there exist two constants $\gamma_1, \gamma_2 > 0$ s.t. if

$$r(n) \geq \gamma_1 \sqrt{\frac{\log n}{n}} \quad \text{and} \quad c(n) = \gamma_2 \log \frac{1}{r(n)}$$

then the *expansion* of $BT(r(n), c(n))$ is, w.h.p.,

$$\lambda(s) = \begin{cases} \Theta(\min\{c(n), m/s\}) & \text{if } 1 \leq s \leq \alpha m \\ \Theta(\sqrt{m/s}) & \text{if } \alpha m < s \leq n/2. \end{cases}$$

Diameter of $BT(r(n), c(n))$

Definition (Diameter)

$$\text{diam}(G) = \max \{ \text{dist}(u, v) : u, v \in V(G) \}$$

Theorem (Diameter of BT)

There exist two positive real constants γ_1, γ_2 such that if

$$r(n) \geq \gamma_1 \sqrt{\frac{\log n}{n}} \quad \text{and} \quad c(n) = \gamma_2 \log \frac{1}{r(n)}$$

then the *diameter* of $BT(r(n), c(n))$ is, w.h.p.,

- ▶ $\text{diam}(BT) = O(1/r(n) + \log n)$
- ▶ $\text{diam}(BT) = \Omega(1/r(n))$ (tight for $r(n) = O(1/\log n)$)
- ▶ $\text{diam}(BT) = \Omega(\log n / \log \log n)$ for $r(n) = \Theta(1)$.

Dynamic Bluetooth Topology

“Definition” of $\mathcal{G}(n, \rho, r(n), c(n))$

Sequence of Markovian Evolving Graphs $\{G_t\}_{t \in \mathbb{N}}$, where the edge-set of G_t is selected according to the $\text{BT}(r(n), c(n))$ protocol, and each node moves in a time step u.a.r. within a ball of radius ρ

Theorem (Flooding Time of DBT)

There exist two positive real constants γ_1, γ_2 such that if

$$r(n) \geq \gamma_1 \sqrt{\frac{\log n}{n}} \quad \text{and} \quad c(n) = \gamma_2 \log \frac{1}{r(n)}$$

*then the **flooding time** of $\mathcal{G}(n, \rho, r(n), c(n))$ is, w.h.p.,*

$$T_{FL} = O\left(\frac{1}{r(n)} + \log n\right).$$

Extensions & Open Problems

- ▶ Extensions

- ▶ When $r(n) = \Theta\left(\sqrt{\log n/n}\right)$ (minimum radius),
 $c(n) = \Theta\left(\sqrt{\log n/\log \log n}\right)$ is the minimum number of neighbors needed to achieve connectivity w.h.p. (Broutin et al. [arXiv'11])
- ▶ Generalization to higher dimensions

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- ▶ Open problems

- ▶ Complete characterization of the trade-off between $r(n)$ and $c(n)$
- ▶ Studying how expansion and diameter behave in the above case

Dynamic Graphs



Mobile Networks: a Closer Look

Mobile networks are distributed systems

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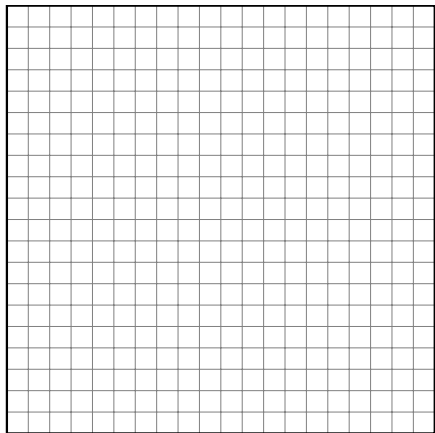
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- ▶ . . . but not too fast: mobility speed \ll transmission speed
- ▶ with no infrastructure: **wireless**, multi-hop communications
- ▶ under energy constraints: **small transmission radius**
- ▶ essentially **planar**

Previous Work

- ▶ Alves *et al.* [Ann.App.Pr.'02] and Kesten *et al.* [Ann.Pr.'05]
 - ▶ shape of the subspace of \mathbb{Z}^d containing “infected” RWs (Frog Model)
- ▶ Dimitriou *et al.* [Dis.App.Mat.'06]
 - ▶ k agents performing RWs on an n -node graph, bounds on the expected infection time, depending on graph expansion
- ▶ Clementi *et al.* [ICALP'09, IPDPS'09]
 - ▶ $k = \Theta(n)$ agents on a n -node 2D grid (dense scenario)
 - ▶ large maximum speed R and/or large transmission radius r
 - ▶ bounds on broadcast time
- ▶ Peres *et al.* [SODA'11]
 - ▶ Poisson point process in \mathbb{R}^d above percolation threshold
 - ▶ agents follow Brownian motion
 - ▶ bounds on detection, coverage, broadcast time

Mobility Model

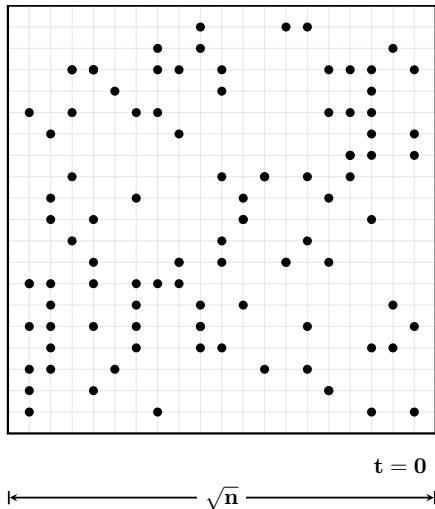
- ▶ $\sqrt{n} \times \sqrt{n}$ 2D grid w/ loops



← \sqrt{n} →

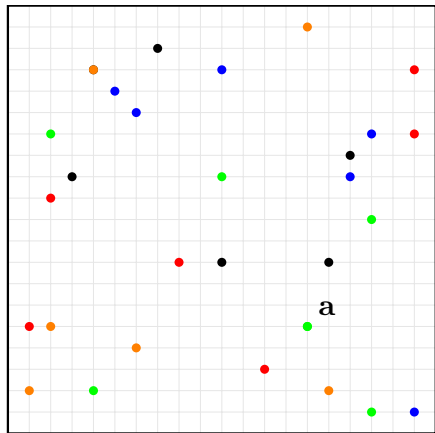
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- ▶ $\sqrt{n} \times \sqrt{n}$ 2D grid w/ loops
- ▶ $k = O(n)$ mobile agents
- ▶ Initial positions \equiv stationary distribution (\Rightarrow uniform)



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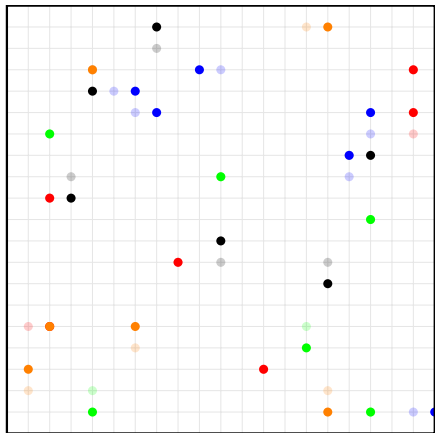
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- ▶ Independent, simple, discrete-time random walks
- ▶ $pos_a(t) \equiv$ position of agent a at time $t \in \mathbb{N}$



$t = 0$

Mobility Model

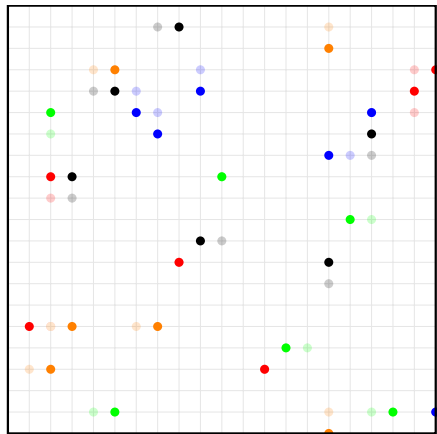
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$t = 1$

Mobility Model

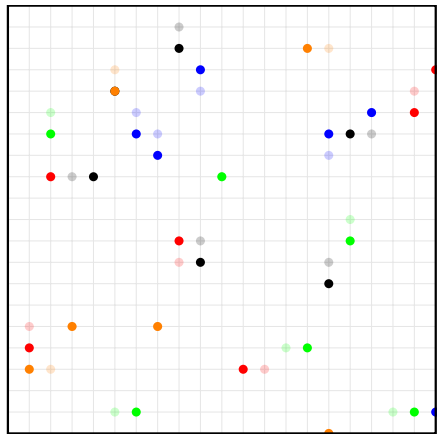
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$t = 2$

Mobility Model

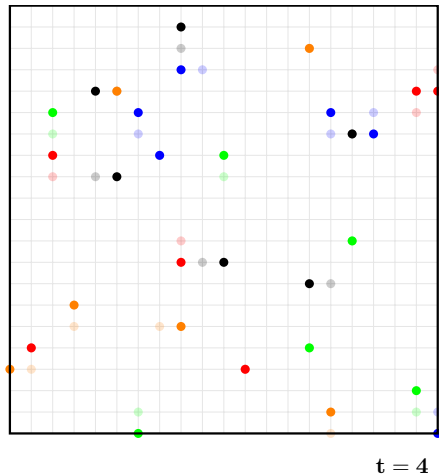
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$t = 3$

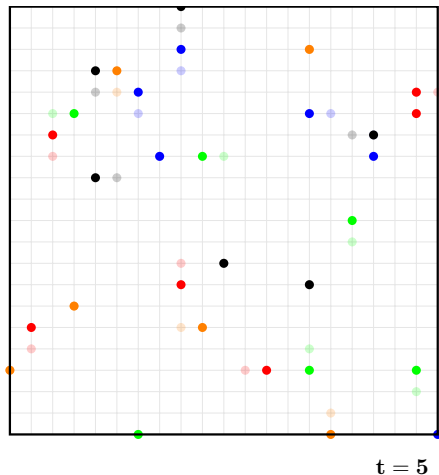
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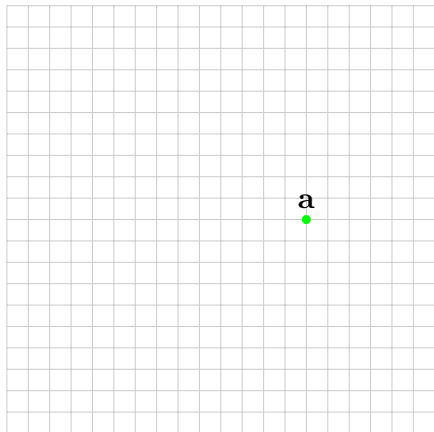
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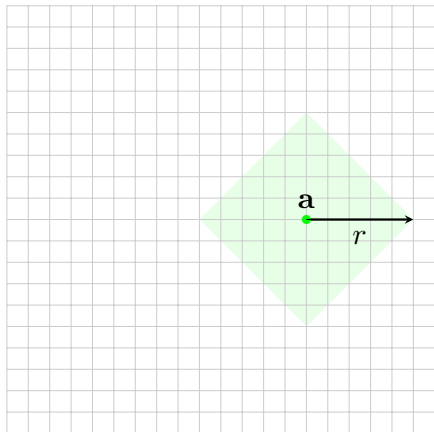
Communication Model

- ▶ Each agent has transmission radius $r \geq 0$



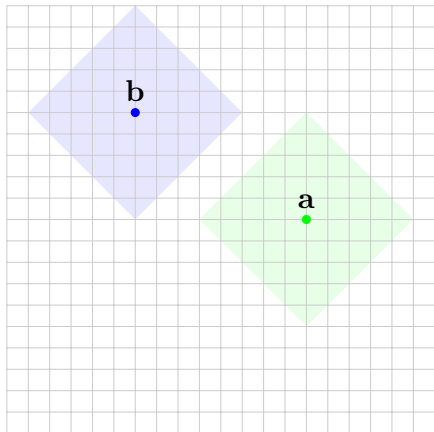
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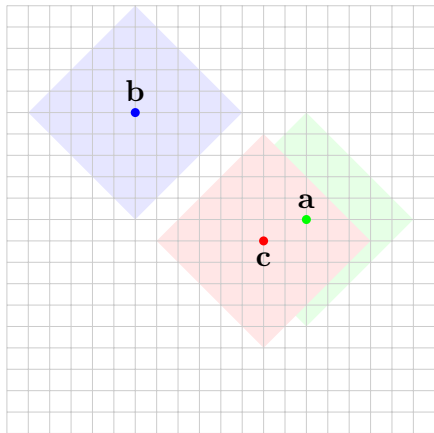
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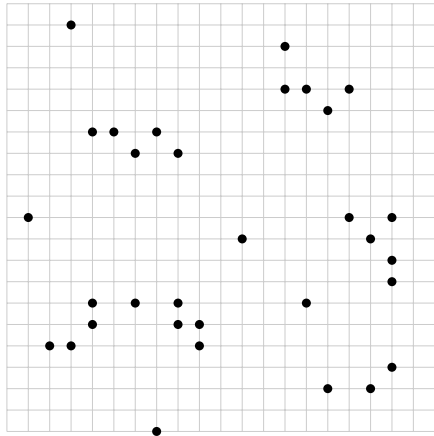
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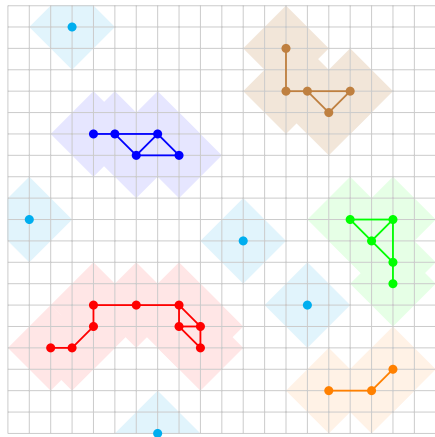
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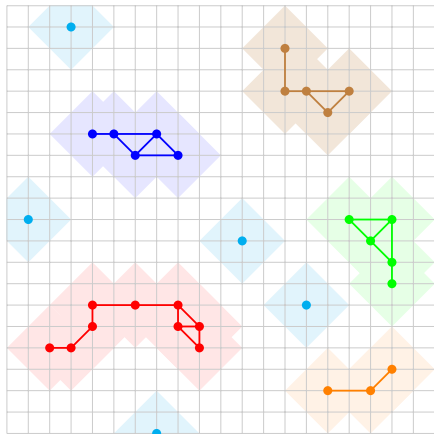
- ▶ Each agent has transmission radius $r \geq 0$
- ▶ Visibility graph $G_t(r)$:
 - ▶ vertices \equiv agents
 - ▶ edge $\{a, a'\} \in G_t(r) \iff \|pos_a(t) - pos_{a'}(t)\| \leq r$
 - ▶ each connected component is called “island”



$G_t(r)$

Communication Model

- ▶ $M_a(t) \equiv$ messages known by a at time t
- ▶ $M_a(t)$ is non-decreasing (agents don't forget messages)
- ▶ On a meeting, agents exchange *all* the messages they know



$$G_t(r)$$

Broadcast Time

Initially, only the **source** s knows the rumor \mathcal{M} :

$$M_s(0) = \{\mathcal{M}\} \quad \text{and} \quad M_a(0) = \emptyset \quad \forall a \neq s$$

We study the **Broadcast Time** T_B of the system, which is the first time instant when all the agents know the rumor:

$$T_B = \inf\{t \geq 0 : \mathcal{M} \in M_a(t) \quad \forall a\}$$

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Remarks

- ▶ $T_B \equiv T_B(n, k, r)$
- ▶ T_B is non-increasing in r : $r' \geq r \Rightarrow T_B(r') \leq T_B(r)$
- ▶ Broadcast analysis extends to other communication primitives

Our Contribution [PODC'11]

- ▶ Tight bounds on the **broadcast time** T_B of a message in a **sparse** system of mobile agents
- ▶ Our analysis techniques extend to several **related models** (dense case, multiple messages, different interaction rules, ...)

Upper Bound on T_B

Theorem 1 (Upper Bound on T_B)

Let $r = 0$ (physical meetings). Then, for $k \geq 2$,

$$T_B = \tilde{O}\left(\frac{n}{\sqrt{k}}\right)$$

with probability $\geq 1 - 1/n^2$.

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with probability $\geq 1 - 1/n^2$.

Since $T_B(r)$ is non-increasing:

Corollary 1

$T_B = \tilde{O}\left(n/\sqrt{k}\right)$ w.h.p. for any $k \geq 2$, $r \geq 0$.

Quite surprisingly, this bound is essentially **tight** (see next slide)

Lower Bound on T_B

Theorem 2 (Lower Bound on T_B)

Let $r \leq \frac{1}{8e^3} \sqrt{n/k}$. Then, for $k \geq 2$,

$$T_B = \tilde{\Omega} \left(\frac{n}{\sqrt{k}} \right)$$

with probability $\geq 1 - (2^{-(k-1)} + 1/n + 2/n^2)$.

Lower Bound on T_B

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Together with Corollary 1, we have the **tight** result:

Corollary 2

If $k = \Omega(\log n)$ and $r \leq \frac{1}{8e^3} \sqrt{n/k}$, then $T_B = \tilde{\Theta} \left(n/\sqrt{k} \right)$ w.h.p.

Extensions & Open Problems

- ▶ Our analysis techniques extend to
 - ▶ dense scenarios ($k \geq n/2$)
 - ▶ other communication primitives (gossip, multicast)
 - ▶ related models (Frog Model, mobility with jumps, predator-prey)

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 - ▶ related models (Frog Model, mobility with jumps, predator-prey)
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- ▶ Open problems
 - ▶ Modeling barriers and obstacles
 - ▶ More realistic mobility models
 - ▶ Tradeoffs between communication complexity and spreading time
 - ▶ Tradeoffs between agent's buffer size and spreading time

Conclusions



Contribution of this Thesis

- ▶ Bluetooth Topology
 - ▶ Tight bounds on expansion
 - ▶ Tight bounds (up to a log additive factor) on diameter
 - ▶ Upper bound on flooding time in dynamic Bluetooth networks

- ▶ Dynamic Graphs
 - ▶ Tight bounds (up to polylog factors) on the broadcast time of a message in sparse mobile networks
 - ▶ Our analysis techniques apply to several related scenarios

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Alberto Pettarin
pettarin@dei.unipd.it

List of Publications



- ▶ A. P., A. Pietracaprina, G. Pucci
On the Expansion and Diameter of Bluetooth-Like Topologies, ESA, 2009
- ▶ P. Bertasi, A. P., M. Scquizzato, F. Silvestri
A Novel Resource-Driven Job Allocation Scheme for Desktop Grid Environments, TGC, 2010
- ▶ A. P., A. Pietracaprina, G. Pucci, E. Upfal
Infectious Random Walks, arXiv, 2010
- ▶ A. P., A. Pietracaprina, G. Pucci, E. Upfal
Tight Bounds on Information Dissemination in Sparse Mobile Networks, PODC, 2011
- ▶ A. P.
Note on the Mixing Time of the Ball Walk, Unpublished note, 2011
- ▶ A. P., E. Upfal
Dynamic Line-of-Sight Networks, Work in progress, 2011–2012
- ▶ A. P., A. Pietracaprina, G. Pucci
On the Expansion and Diameter of Bluetooth-Like Topologies, ToCS, 2012